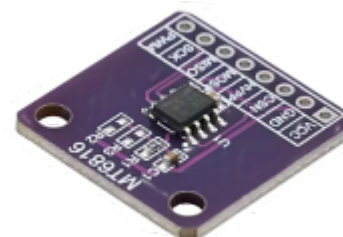


# Magnetic angle sensors

A magnetic angle sensor is a contactless electronic device used to measure the rotational position of a shaft or object. It works by detecting the orientation of a magnetic field—usually from a small permanent magnet attached to the rotating part—and converting that physical position into a digital or analog signal.



## How It Works

- **The Magnet:** A simple dipole (North/South) magnet is mounted on the end or side of a rotating shaft.
- **The Sensing Element:** An integrated circuit (IC) is placed close to the magnet. It uses physical phenomena such as the Hall Effect and magnetoresistance (AMR/GMR/TMR) to detect the direction of magnetic flux lines.
- **The Processor:** The sensor’s internal logic calculates the precise angle (0° to 360°) based on the field strength across multiple internal axes and outputs that data via interfaces like SPI, I<sup>2</sup>C, or PWM.

## Technical Comparison of Several Typical Magnetic Angle Sensors

Feature	AS5047P	AS5600	MT6701	MT6816	MT6835	TLE5012B
<b>Max Resolution</b>	14-bit (SPI)	12-bit (I <sup>2</sup> C)	14-bit (I <sup>2</sup> C/SSI)	14-bit (SPI)	21-bit (SPI)	15-bit (SSC/SPI)
<b>Interfaces</b>	SPI, ABI, UVW, PWM	I <sup>2</sup> C, PWM, Analog	I <sup>2</sup> C, SSI, ABZ, UVW, PWM	SPI, ABZ, UVW, PWM	SPI, ABZ, UVW, PWM	SSC (SPI), IIF, HSM, PWM
<b>Max Speed (RPM)</b>	28,000	Low speed (potentiometer)	55,000	25,000	120,000	~10,000+
<b>Latency</b>	< 1 μs (DAEC)	High (I2C)	< 5 μs	< 2 μs Ultra-low	Low	
<b>Accuracy (Typ)</b>	±0.34° at speed	±0.5° (static)	±1.0°	High precision	Micro-level	±1.0°
<b>Best For</b>	High-speed BLDC	Contactless Knobs	General Purpose	Standard Robotics	High-end Servo	Automotive/Industrial

## Key Product Highlights

- **ams OSRAM AS5047P:** Noted by experts for its Dynamic Angle Error Compensation (DAEC), which maintains accuracy even at 28,000 RPM.
- **ams OSRAM AS5600:** A popular, low-cost choice for contactless potentiometers and battery-powered devices due to its simple I2C interface and low power modes.
- **MagnTek MT6701:** Often cited as a superior AS5600 replacement; it offers higher 14-bit resolution and much higher speed support (55k RPM) while remaining affordable.
- **MagnTek MT6835:** A high-performance 21-bit sensor that delivers over 2 million steps per revolution, making it ideal for micro-level accuracy in professional robotics.
- **Infineon TLE5012B:** Praised for its robustness in extreme environments (-40°C to +150°C)

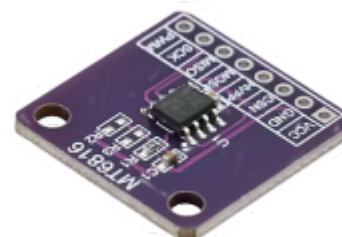
and stable readings under high heat.

## Common Sensor Types

- **Hall Effect Sensors:** The most widely used type. According to Allegro MicroSystems, these are often integrated into single-chip CMOS solutions like the Allegro A33002, making them cost-effective for general motor control and automotive steering.
- **Anisotropic Magnetoresistance (AMR):** These sensors, such as the Honeywell HMC1501, are prized for high precision. A key limitation noted by Infineon is that a standard AMR element is unique only over a 180° range, often requiring additional logic or sensors to achieve full 360° detection.
- **Giant Magnetoresistance (GMR):** Based on multi-layer thin films, GMR sensors like the Infineon TLE5012B offer a much higher signal-to-noise ratio than Hall sensors. Experts at Alif Sensor highlight that GMR was a Nobel Prize-winning discovery that allowed for extreme miniaturization.
- **Tunnel Magnetoresistance (TMR):** The newest and most advanced type. TDK-Micronas states that TMR sensors (e.g., the TDK TAD2141) provide 500 times the output of a Hall element while consuming significantly less power, making them ideal for battery-operated and high-reliability automotive systems.

## MT-6816

The MagnTek MT6816 is a high-speed, 14-bit magnetic angle sensor IC based on advanced *Anisotropic Magnetoresistive (AMR)* technology. It is specifically designed to provide absolute 0°–360° angle sensing for high-performance applications like BLDC motor control and robotics.



## Core Technical Specifications

According to official technical documents from MagnTek and Novosense, the sensor features the following primary specifications:

- **Resolution:** 14-bit absolute angle resolution (16,384 steps per revolution).
- **Maximum Speed:** Supports rotation speeds up to 25,000 RPM.
- **System Latency:** Ultra-low propagation delay of less than 2 μs.
- **Operating Voltage:** 3.0V to 5.5V DC.
- **Supply Current:** Typically 10mA.
- **Operating Temperature:** Industrial range from -40°C to +125°C.
- **Magnetic Flux Density:** Operates within a range of 30 mT to 1,000 mT.

## MT-6816 Pinout

Pin	Pin Name	Type	
1	CSN	Input	Chip Select (Active Low) for SPI communication
2	SCK	Input	Serial Clock input for SPI
3	SDO	Output	Serial Data Output (MISO) for SPI
4	SDI / SDA	I/O	Serial Data Input (MOSI) for 4-wire SPI, or Data I/O for 3-wire SPI

Pin	Pin Name	Type	
5	TEST / PWM	Output	PWM absolute angle output; also used as a factory test pin
6	OUT / Z / W	Output	Z-index for ABZ mode, or W phase for UVW mode
7	VSS	Power	Ground (0V)
8	VDD	Power	Supply Voltage (3.0V to 5.5V)

### Pin Functionality by Mode

The output pins (Pins 5 and 6) and the SPI pins change behavior based on your interface choice:

- **SPI Mode:** Uses Pins 1-4 for data transfer. It supports both 3-wire (sharing SDI/SDO) and 4-wire configurations.
- **Incremental Mode (ABZ):** Pin 6 provides the Z (Index) pulse, while internal programming determines which pins output the A and B quadrature signals (often multiplexed on the SPI lines when SPI is not active).
- **Motor Commutation (UVW):** Pin 6 provides the W phase, replacing traditional Hall effect sensor signals for brushless motors.

### Connection Notes

- **Power Supply:** Place a 0.1µF decoupling capacitor as close as possible between VDD (Pin 8) and VSS (Pin 7) to ensure stable readings.
- **Magnet Placement:** The magnet should be centered over the SOP-8 package's geometric center for maximum accuracy.
- **SPI Settings:** For microcontroller communication, use SPI Mode 3 (CPOL=1, CPHA=1) with MSB first.

### Arduino example

To read the 14-bit absolute angle from the MagnTek MT6816 using an Arduino, you use the SPI interface. The sensor requires SPI Mode 3 (CPOL=1, CPHA=1) and a clock speed up to 16MHz.

### Arduino Wiring

Connect the MT6816 to your Arduino (e.g., Uno/Nano) as follows:

- VDD (Pin 8) → 3.3V or 5V
- VSS (Pin 7) → GND
- CSN (Pin 1) → D10 (Chip Select)
- SCK (Pin 2) → D13 (Serial Clock)
- SDO (Pin 3) → D12 (MISO)
- SDI (Pin 4) → D11 (MOSI)

### Example Sketch

This code initializes the SPI bus and reads the absolute angle from registers 0x03 and 0x04

```
#include <SPI.h>

const int CS_PIN = 10;
const byte READ_REG_03 = 0x83; // Read command for Register 0x03
```

```
void setup() {
  Serial.begin(115200);
  pinMode(CS_PIN, OUTPUT);
  digitalWrite(CS_PIN, HIGH);

  SPI.begin();
}

void loop() {
  uint16_t angle = readMT6816();

  // Convert 14-bit raw value (0-16383) to degrees (0-360)
  float degrees = (angle * 360.0) / 16384.0;

  Serial.print("Raw: ");
  Serial.print(angle);
  Serial.print(" | Angle: ");
  Serial.println(degrees);

  delay(100);
}

uint16_t readMT6816() {
  // MT6816 requires SPI Mode 3, MSB first, max 16MHz
  SPI.beginTransaction(SPISettings(1000000, MSBFIRST, SPI_MODE3));

  digitalWrite(CS_PIN, LOW);

  // Step 1: Send read command for the first register
  SPI.transfer(READ_REG_03);

  // Step 2: Read two bytes
  uint8_t highByte = SPI.transfer(0x00);
  uint8_t lowByte = SPI.transfer(0x00);

  digitalWrite(CS_PIN, HIGH);
  SPI.endTransaction();

  // Combine bytes: The 14-bit angle is in highByte and bits [7:2] of
  lowByte
  uint16_t rawData = (highByte << 8) | lowByte;
  uint16_t angle = (rawData & 0x3FFF); // Mask to 14 bits

  return angle;
}
```

## Key Coding Details

- **Register Access:** The absolute angle data is stored in registers 0x03 and 0x04. Sending 0x83

(Read bit + address 0x03) allows you to burst-read both bytes.

- **Data Masking:** The sensor provides 14-bit data. The result must be masked with 0x3FFF to remove any parity or error flags stored in the remaining bits.
- **Parity Check (Optional):** For high-reliability applications, you can verify the parity bit (typically bit 15) to ensure the data wasn't corrupted during transmission.

## MT-6835

The MagnTek MT6835 is a fourth-generation magnetic angle encoder IC that significantly improves upon the MT6816, offering higher resolution and specialized calibration features. Based on *Anisotropic Magnetoresistive (AMR)* technology, it is designed for ultra-high-precision applications such as absolute-value servo motor control and high-speed robotics.



### Technical Specifications

According to data from MagnTek and Novosense, the MT6835 features the following core parameters:

- **Resolution:** 21-bit absolute angle resolution (over 2 million steps per revolution).
- **Maximum Speed:** Supports high-speed rotation up to 120,000 RPM.
- **Accuracy (INL):**
  - **Factory Default:**  $< \pm 0.5^\circ$ .
  - **After Self-Calibration:** Typical accuracy of  $\pm 0.07^\circ$ .
  - **With NLC Mode:** Typical accuracy of  $\pm 0.02^\circ$ .
- **System Latency:** 2  $\mu$ s to 10  $\mu$ s propagation delay.
- **Operating Voltage:** 3.0V to 5.5V DC (3.3V to 5.0V typical).
- **Operating Temperature:** Industrial range from  $-40^\circ\text{C}$  to  $+125^\circ\text{C}$ .

### Output Interfaces

The MT6835 provides several independent output modes, making it a versatile replacement for optical encoders:

- **SPI:** Standard 4-wire interface supporting up to 16 MHz clock frequency for reading 21-bit angle data.
- **Incremental ABZ:** Programmable resolution from 1 to 16,384 lines (pulses per revolution).
- **Incremental UVW:** Supports any resolution from 1 to 16 pole pairs.
- **PWM:** 12-bit absolute angle output.

### MT6835 Pinout

Pin	Pin Name	Type	Function Description
1	U / CAL	Output/Input	U phase for UVW mode; also used as an Auto-Calibration trigger
2	V	Output	V phase for UVW commutation mode
3	W	Output	W phase for UVW commutation mode
4	VSS	Power	Ground (0V)

Pin	Pin Name	Type	Function Description
5	PWM	Output	12-bit Pulse Width Modulation absolute angle output
6	A	Output	A channel for incremental ABZ quadrature mode
7	B	Output	B channel for incremental ABZ quadrature mode
8	Z	Output	Z (Index) pulse for incremental ABZ mode
9	MISO	Output	Master In Slave Out for SPI communication (4-wire)
10	MOSI	Input	Master Out Slave In for SPI communication (4-wire)
11	SCK	Input	Serial Clock for SPI (up to 16MHz)
12	CSN	Input	Chip Select (Active Low) for SPI
13	VDD	Power	Supply Voltage (3.0V to 5.5V)
14	VOUT	Power	Internal LDO output (typically connected to a decoupling capacitor)
15	NC	—	No Internal Connection (Leave floating)
16	NC	—	No Internal Connection (Leave floating)

## Key Hardware Considerations

- **Decoupling:** It is critical to place a 100 nF (0.1 µF) capacitor between VDD (Pin 13) and VSS (Pin 4), and another capacitor on the VOOUT (Pin 14) pin, for internal voltage stability.
- **Calibration Pin:** Pin 1 (CAL) can be used to trigger the built-in self-calibration routine, which is unique to the MT6835 and improves its accuracy to  $\pm 0.07^\circ$ .
- **Independent Outputs:** Unlike the MT6816, which often shares pins, the MT6835 allows you to use SPI and ABZ/UVW outputs simultaneously without pin multiplexing conflicts.

## MT-6835 Arduino example code

To read the 21-bit absolute angle from the MT6835, you must use the SPI interface. Because 21 bits exceed a standard 16-bit integer, you will need to store the data in a `uint32_t`.

## Wiring (MT-6835 to Arduino)

- VDD (Pin 13) → 3.3V or 5V
- VSS (Pin 4) → GND
- CSN (Pin 12) → D10
- SCK (Pin 11) → D13
- MISO (Pin 9) → D12
- MOSI (Pin 10) → D11

## Example code

The MT6835 stores its 21-bit angle across three registers starting at 0x03.

```
#include <SPI.h>

const int CS_PIN = 10;
const byte READ_CMD = 0x83; // Read bit (0x80) + Register address (0x03)

void setup() {
  Serial.begin(115200);
  pinMode(CS_PIN, OUTPUT);
  digitalWrite(CS_PIN, HIGH);
}
```

```
SPI.begin();
}

void loop() {
  uint32_t rawAngle = readMT6835();

  // Convert 21-bit (0 to 2,097,151) to degrees
  float degrees = (rawAngle * 360.0) / 2097152.0;

  Serial.print("21-bit Raw: ");
  Serial.print(rawAngle);
  Serial.print(" | Angle: ");
  Serial.println(degrees, 4); // 4 decimal places for precision

  delay(50);
}

uint32_t readMT6835() {
  // MT6835 SPI: Mode 3, MSB first, up to 16MHz
  SPI.beginTransaction(SPISettings(8000000, MSBFIRST, SPI_MODE3));
  digitalWrite(CS_PIN, LOW);

  SPI.transfer(READ_CMD);
  uint32_t b1 = SPI.transfer(0x00); // Bits 20-13
  uint32_t b2 = SPI.transfer(0x00); // Bits 12-5
  uint32_t b3 = SPI.transfer(0x00); // Bits 4-0 + Status bits

  digitalWrite(CS_PIN, HIGH);
  SPI.endTransaction();

  // Combine the bytes:
  // The 21-bit angle is packed into the 24 bits of data returned.
  // Format: [Byte1: 8 bits][Byte2: 8 bits][Byte3: 5 bits + 3 status bits]
  uint32_t combined = (b1 << 16) | (b2 << 8) | b3;
  uint32_t angle = combined >> 3; // Shift right by 3 to remove status bits

  return angle;
}
```

## Critical Implementation Details

- **Bit Packing:** The sensor returns 3 bytes (24 bits). The top 21 bits are the angle, while the bottom 3 bits are status flags (like No-Magnet or Over-speed errors).
- **SPI Mode:** Like its predecessor, the MT6835 uses SPI Mode 3. If you get oscillating or “garbage” data, double-check your CPOL/CPHA settings.
- **High Resolution:** Because 21-bit resolution is extremely sensitive (0.00017° per step), even tiny vibrations or magnetic noise will cause the last few digits to flicker.

## Sensor topics on lamaPLC

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<ul style="list-style-type: none"> <li>• <a href="#">lamaPLC project: Arduino - Vibration sensors</a></li> </ul>	2026/04/15 17:21	<a href="#">vibration</a> , <a href="#">sensor</a> , <a href="#">piezoelectric</a> , <a href="#">mems</a> , <a href="#">eddy-current</a> , <a href="#">electrodynamic</a> , <a href="#">gxfm0459</a> , <a href="#">ldtm-028k</a> , <a href="#">arduino</a> , <a href="#">arduino code</a>
<ul style="list-style-type: none"> <li>• <a href="#">lamaPLC project: Digitales Potentiometer Board Moduls</a></li> </ul>	2026/04/11 18:29	<a href="#">sensor</a> , <a href="#">module</a> , <a href="#">arduino code</a> , <a href="#">renesas</a> , <a href="#">x9c series</a> , <a href="#">x9c102</a> , <a href="#">x9c103</a> , <a href="#">x9c104</a> , <a href="#">x9c503</a> , <a href="#">xdcp</a> , <a href="#">digitally controlled potentiometer</a>
<ul style="list-style-type: none"> <li>• <a href="#">lamaPLC project: Sension SCD CO<sup>2</sup> measurement module</a></li> </ul>	2026/04/15 19:34	<a href="#">scd30</a> , <a href="#">scd40</a> , <a href="#">scd41</a> , <a href="#">iaq</a> , <a href="#">ndir</a> , <a href="#">sensor</a> , <a href="#">i2c</a> , <a href="#">arduino code</a>
<ul style="list-style-type: none"> <li>• <a href="#">lamaPLC: A0221AU / A02YYUW Waterproof Ultrasonic Distance Sensor with UART communication</a></li> </ul>	2026/04/23 21:52	<a href="#">a0221au</a> , <a href="#">a02yyuw</a> , <a href="#">waterproof</a> , <a href="#">ultrasonic</a> , <a href="#">distance</a> , <a href="#">sensor</a> , <a href="#">uart</a> , <a href="#">ip67</a> , <a href="#">serial</a> , <a href="#">sen0311</a> , <a href="#">dfrobot</a>
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<ul style="list-style-type: none"> <li>• <a href="#">LamaPLC: Allegro ACS758 Hall-effect linear current sensors</a></li> </ul>	2026/04/23 21:52	<a href="#">cjmcu</a> , <a href="#">cjmcu-758</a> , <a href="#">acs758</a> , <a href="#">acs758lcb-050b</a> , <a href="#">acs758lcb-100b</a> , <a href="#">acs758kcb-150b</a> , <a href="#">acs758ecb-200b</a> , <a href="#">hall-effect</a> , <a href="#">current</a> , <a href="#">sensor</a> , <a href="#">analog</a> , <a href="#">arduino</a> , <a href="#">code</a>
<ul style="list-style-type: none"> <li>• <a href="#">LamaPLC: APDS - Avago ALS and proximity detection sensors with I<sup>2</sup>C communication</a></li> </ul>	2026/04/23 21:52	<a href="#">avago</a> , <a href="#">apds-9900</a> , <a href="#">apds-9930</a> , <a href="#">apds-9960</a> , <a href="#">als</a> , <a href="#">proximity</a> , <a href="#">detection</a> , <a href="#">gesture recognition</a> , <a href="#">gesture</a> , <a href="#">i2c</a> , <a href="#">communication</a> , <a href="#">sensor</a> , <a href="#">arduino</a> , <a href="#">code</a>
<ul style="list-style-type: none"> <li>• <a href="#">lamaPLC: AS5600 Magnetic Induction Angle Measurement Sensor Module</a></li> </ul>	2026/03/28 23:50	<a href="#">communication</a> , <a href="#">i2c</a> , <a href="#">as5600</a> , <a href="#">as-5600</a> , <a href="#">magnetic</a> , <a href="#">induction</a> , <a href="#">angle</a> , <a href="#">sensor</a>
<ul style="list-style-type: none"> <li>• <a href="#">LamaPLC: BMP/BME Bosch Temperature/Humidity/Pressure sensors with I<sup>2</sup>C communication</a></li> </ul>	2026/04/23 21:52	<a href="#">bme280</a> , <a href="#">bme680</a> , <a href="#">bmp180</a> , <a href="#">bmp280</a> , <a href="#">hw-611</a> , <a href="#">hw611</a> , <a href="#">bosch</a> , <a href="#">temperature</a> , <a href="#">humidity</a> , <a href="#">pressure</a> , <a href="#">sensor</a> , <a href="#">arduino</a> , <a href="#">i2c</a> , <a href="#">communication</a> , <a href="#">cjmcu</a>
<ul style="list-style-type: none"> <li>• <a href="#">LamaPLC: BQ25570 / CJMCU-2557 - Texas Instruments nano-power management IC and module</a></li> </ul>	2026/04/23 21:52	<a href="#">bq25570</a> , <a href="#">sensor</a> , <a href="#">texas instruments</a> , <a href="#">nano-power management</a> , <a href="#">dc-dc boost charger</a> , <a href="#">mppt</a> , <a href="#">solar</a> , <a href="#">thermoelectric</a> , <a href="#">piezoelectric</a>
<ul style="list-style-type: none"> <li>• <a href="#">LamaPLC: CJMCU-219/INA-219 breakout board/IC with I<sup>2</sup>C communication</a></li> </ul>	2026/04/23 21:52	<a href="#">cjmcu-219</a> , <a href="#">ina-219</a> , <a href="#">ina219</a> , <a href="#">breakout board</a> , <a href="#">i2c</a> , <a href="#">communication</a> , <a href="#">sensor</a> , <a href="#">voltage</a> , <a href="#">current</a> , <a href="#">arduino</a> , <a href="#">code</a> , <a href="#">cjmcu</a>
<ul style="list-style-type: none"> <li>• <a href="#">LamaPLC: CJMCU-3216 / AP-3216 integrated digital ambient light and proximity sensor module/IC with I<sup>2</sup>C communication</a></li> </ul>	2026/04/23 21:52	<a href="#">cjmcu-3216</a> , <a href="#">cjmcu</a> , <a href="#">ap-3216</a> , <a href="#">ap3216</a> , <a href="#">ambient light</a> , <a href="#">proximity</a> , <a href="#">sensor</a> , <a href="#">arduino</a> , <a href="#">code</a> , <a href="#">i2c</a> , <a href="#">communication</a>

• LamaPLC: CJMCU-3901/PMW-3901 compact optical flow sensor module/IC by PixArt with SPI communication	2026/04/23 21:52	cjmcu-3901, cjmcu, pmw3901, pmw-3901, optical flow, sensor, pixart, spi, communication, arduino, code, pmw3901mb-txqt
• LamaPLC: CJMCU-6701: Biosensor for measuring Galvanic Skin Response (GSR) with SPI communication	2026/04/23 21:52	cjmcu, cjmcu-6701, acs758, acs-758, galvanic skin response, gsr, electrodermal activity, eda, spi, communication, arduino, code, sensor, healthcare
• LamaPLC: CJMCU-6814 combined gas sensor module for CO, NO <sub>2</sub> , NH <sub>3</sub>	2026/04/23 21:52	analog, cjmcu, cjmcu-6814, mics6814, mics-6814, sensor, arduino, code, carbon monoxide, co, ammonia, nh <sub>3</sub> , nitrogen dioxide, no <sub>2</sub>
• lamaPLC: CJMCU-811 CCS811 Gas Sensor (VOCs TVOC CO <sub>2</sub> )	2026/03/22 00:08	cjmcu-811, ccs811, gas, sensor, vocs, tvoc, eco2, co2, arduino, air quality metal oxide, mox, i2c
• LamaPLC: CJMCU-8221 Analog Devices Precision instrumentation amplifier module	2026/04/23 21:52	cjmcu-8221, ad8221ar, analog devices, amplifier, sensor, cjmcu
• LamaPLC: D6T Omron Non-Contact Thermal Sensors with I <sup>2</sup> C communication	2026/04/23 21:52	d6t, d6t-32l, d6t-44l, d6t-8l, d6t-1a, omron, non-contact, thermal, sensor, i2c, arduino, code
• LamaPLC: DHT Temperature /Humidity sensors with 1-wire / I <sup>2</sup> C communication	2026/04/23 21:52	dht11, dht20, dht22, temperature, humidity, pressure, sensor, 1-wire, arduino, code
• LamaPLC: DPS Infineon Temperature/Pressure sensors with I <sup>2</sup> C communication	2026/04/23 21:52	dps310, infineon, temperature, pressure, sensor, arduino, i2c, communication, code
• lamaPLC: DS18B20 1-Wire Digital Thermometer	2026/04/23 21:52	ds18b20, sensor, 1-wire, communication, arduino, thermometer, parasitic mode
• lamaPLC: Energy, power, current, and voltage	2025/05/31 23:32	i2c, i c, communication, arduino, energy, power, current, sensor, ina226
• LamaPLC: ENS ScioSense Multi-gas sensors with I <sup>2</sup> C communication	2026/04/23 21:52	ens160, sciosense, gas-quality, i2c, communication, sensor, arduino, code, eco <sub>2</sub> , tvoc, aqi, indoor air quality, iaq, co <sub>2</sub> , voc
• lamaPLC: ENS160 + AHT21 Air Quality Sensor - CO, ECO, TVOC, Temp & Humidity Module	2026/04/23 21:52	arduino, ens160, aht21, air quality, sensor, co, eco, tvoc, module, aqi
• LamaPLC: Gas sensors	2023/07/01 17:29	gas, sensor, i2c, onewire, communication, mq-3, mq-4, mq-5, mq-6, mq-7, mq-8, mq-9, mq-135, gm-102b, gm-302b, gm-502b, gm-702b, alcohol, ch <sub>4</sub> , natural gas, smoke, lng, co, co <sub>2</sub> , lpg, h <sub>2</sub> , iso-butane, nox, nh <sub>3</sub> , benzene, town gas, formaldehyde, propane, humidity, temperature, voc, grv gas sens v2

• <a href="#">LamaPLC: GM MEMS Gas-sensors</a>	2026/04/23 21:52	<a href="#">gm-102b</a> , <a href="#">gm-302b</a> , <a href="#">gm-502b</a> , <a href="#">gm-702b</a> , <a href="#">mems</a> , <a href="#">gas-quality</a> , <a href="#">sensor</a> , <a href="#">arduino</a> , <a href="#">code</a> , <a href="#">nitrogen dioxide</a> , <a href="#">no2</a> , <a href="#">volatile organic compounds</a> , <a href="#">voc</a> , <a href="#">carbon monoxide</a> , <a href="#">co</a> , <a href="#">ethyl alcohol</a> , <a href="#">c2h5ch</a> , <a href="#">formaldehyde</a> , <a href="#">ch2o</a> , <a href="#">alcohol</a> , <a href="#">c2h5oh</a>
• <a href="#">lamaPLC: GY-511 6DOF sensor module</a>	2026/03/22 01:44	<a href="#">stmicroelectronics</a> , <a href="#">lsm303dlhc</a> , <a href="#">i2c</a> , <a href="#">lsm303</a> , <a href="#">sensor</a> , <a href="#">gy-511</a> , <a href="#">6dof</a> , <a href="#">pololu</a> , <a href="#">module</a> , <a href="#">arduino</a>
• <a href="#">LamaPLC: HC-SR04 Ultrasonic Sensor Module</a>	2026/04/23 21:52	<a href="#">hc-sr04</a> , <a href="#">ultrasonic</a> , <a href="#">sensor</a> , <a href="#">arduino</a> , <a href="#">code</a>
• <a href="#">LamaPLC: HDC Texas Instruments Temperature/humidity sensors with I<sup>2</sup>C communication</a>	2026/04/23 21:52	<a href="#">sht21</a> , <a href="#">htu21</a> , <a href="#">si7021</a> , <a href="#">gy-21</a> , <a href="#">gy-213v</a> , <a href="#">hdc1080</a> , <a href="#">gy-213v-hdc1080</a> , <a href="#">cjmcu</a> , <a href="#">cjmcu-1080</a> , <a href="#">texas instruments</a> , <a href="#">temperature</a> , <a href="#">humidity</a> , <a href="#">sensor</a> , <a href="#">i2c</a> , <a href="#">communication</a> , <a href="#">arduino</a> , <a href="#">code</a>
• <a href="#">LamaPLC: HTU TE Connectivity temperature/humidity sensors with I<sup>2</sup>C communication</a>	2026/04/23 21:52	<a href="#">htu</a> , <a href="#">htu31d</a> , <a href="#">htu21d</a> , <a href="#">htu20d</a> , <a href="#">sht20</a> , <a href="#">htu20</a> , <a href="#">sht21</a> , <a href="#">htu21</a> , <a href="#">si7021</a> , <a href="#">gy-21</a> , <a href="#">gy-213v</a> , <a href="#">hdc1080</a> , <a href="#">si702</a> , <a href="#">gy-20</a> , <a href="#">sht31</a> , <a href="#">htu31</a> , <a href="#">si7031</a> , <a href="#">gy-31</a> , <a href="#">te connectivity</a> , <a href="#">temperature</a> , <a href="#">humidity</a> , <a href="#">i2c</a> , <a href="#">communication</a> , <a href="#">sensor</a> , <a href="#">arduino</a> , <a href="#">code</a>
• <a href="#">LamaPLC: HX711 24-bit analog-to-digital converter (ADC)</a>	2026/04/11 18:28	<a href="#">hx711</a> , <a href="#">hx-711</a> , <a href="#">analog-to-digital</a> , <a href="#">adc</a> , <a href="#">converter</a> , <a href="#">load cell</a> , <a href="#">wheatstone bridge</a> , <a href="#">weight</a> , <a href="#">sensor</a> , <a href="#">communication</a> , <a href="#">arduino</a> , <a href="#">code</a>
• <a href="#">lamaPLC: INA modules with Arduino libraries</a>	2026/04/11 19:54	<a href="#">i2c</a> , <a href="#">i c</a> , <a href="#">communication</a> , <a href="#">arduino</a> , <a href="#">energy</a> , <a href="#">power</a> , <a href="#">current</a> , <a href="#">monitor</a> , <a href="#">sensor</a> , <a href="#">ina219</a> , <a href="#">gy-219</a> , <a href="#">ina226</a> , <a href="#">gy-216</a> , <a href="#">ina228</a> , <a href="#">gy-228</a> , <a href="#">ina237</a> , <a href="#">ina238</a> , <a href="#">ina260</a> , <a href="#">ina3221</a> , <a href="#">ina</a>
• <a href="#">lamaPLC: INA226 - current/voltage/power monitor with I<sup>2</sup>C communication</a>	2026/04/23 21:52	<a href="#">i2c</a> , <a href="#">i c</a> , <a href="#">communication</a> , <a href="#">arduino</a> , <a href="#">energy</a> , <a href="#">power</a> , <a href="#">current</a> , <a href="#">monitor</a> , <a href="#">sensor</a> , <a href="#">ina226</a> , <a href="#">ina219</a> , <a href="#">ina</a>
• <a href="#">lamaPLC: LTC3588 - Nanopower energy harvesting power supply IC</a>	2026/04/23 21:52	<a href="#">communication</a> , <a href="#">arduino</a> , <a href="#">sensor</a> , <a href="#">energy harvesting</a> , <a href="#">energy</a> , <a href="#">ambient power</a>
• <a href="#">LamaPLC: M01 - V0.4 Laser ranging sensor with UART communication</a>	2026/04/23 21:52	<a href="#">distance measurement</a> , <a href="#">laser</a> , <a href="#">distance</a> , <a href="#">sensor</a> , <a href="#">m01</a>
• <a href="#">LamaPLC: MAX30100/MAX30102 Heart Rate Click Sensor Module</a>	2026/04/23 21:52	<a href="#">max30102</a> , <a href="#">max30100</a> , <a href="#">heart rate click</a> , <a href="#">sensor</a> , <a href="#">communication</a> , <a href="#">i2c</a> , <a href="#">arduino</a> , <a href="#">code</a>
• <a href="#">lamaPLC: Max31865 RTD to Digital Converter - PT100/PT1000 Platine</a>	2026/04/23 21:52	<a href="#">max31865</a> , <a href="#">rtd</a> , <a href="#">pt 100</a> , <a href="#">pt 1000</a> , <a href="#">temperature</a> , <a href="#">spi</a> , <a href="#">platinum</a> , <a href="#">arduino</a> , <a href="#">code</a> , <a href="#">sensor</a> , <a href="#">adafruit</a>
• <a href="#">LamaPLC: MAX4466/MAX9814: Low-noise Microphone Preamplifiers</a>	2026/04/23 21:52	<a href="#">audio</a> , <a href="#">microphone</a> , <a href="#">analogue audio</a> , <a href="#">max4466</a> , <a href="#">max9814</a> , <a href="#">max 4466</a> , <a href="#">max 9814</a> , <a href="#">agc</a> , <a href="#">preamplifiers</a> , <a href="#">sensor</a> , <a href="#">arduino</a> , <a href="#">code</a>

• LamaPLC: MH-Z19 series of NDIR CO <sub>2</sub> sensors	2026/04/23 21:52	mh-z19, mh-z19d, mh-z19c, mh-z19b, mh-z19e, ndir, co <sub>2</sub> , sensor, winsen, uart, pwm, communication, non-dispersive infrared, infrared, ir, temperature, arduino, code, tasmota
• lamaPLC: MPU-6050 (HW-123, GY-521) 6-axis MotionTracking device	2026/03/22 03:13	mpu-6050, hw-123, gy-521, 6-axis motiontracking, dmp, temperature, sensor, mems, arduino code, arduino, accelerometer, gyroscope, tilt
• LamaPLC: MQ Winsen Gas-sensors	2026/04/23 21:52	mq, mq-2, mq-3, mq-4, mq-5, mq-6, mq-7, mq-8, mq-9, mq-131, mq-135, mq-137, winsen, gas-sensor, sensor, arduino, code, alcohol, c <sub>2</sub> h <sub>5</sub> oh, benzine gas, smoke, lpg, propane, c <sub>3</sub> h <sub>8</sub> , hydrogen, h <sub>2</sub> , methane, ch <sub>4</sub> , iso-butane, town gas, ammonia, nh <sub>3</sub>
• LamaPLC: PIR sensors	2026/04/23 21:52	hc-sr501, hc-sr505, am-312, ekmb ekmc, pir, motion, sensor, arduino, code
• LamaPLC: Pixart PAJ7620U2 Gesture recognition sensors/module with I <sup>2</sup> C communication	2026/04/23 21:52	paj7620u2, gy-paj7620, pixart, gesture recognition, i <sup>2</sup> c, communication, sensor, arduino, code
• lamaPLC: PT100 / PT1000	2025/09/23 18:59	pt100, pt1000, temperature, sensor, platine, rtd
• lamaPLC: PTA8C04 4-channel PT100 Modbus Modul	2026/02/14 18:42	pta8c04, sensor, modbus, rtu, rs-485, communication, platine, um72
• LamaPLC: RCWL - Microwave radar sensor	2026/04/23 21:52	rcwl-0516, rcwl, microwave, radar, sensor, arduino, code
• lamaPLC: RD-xx - Ai-Thinker Radar Module with UART communication	2026/04/23 21:52	radar, s3km1110, fmcw, rd-01, rd-03, rd-03d, ai-thinker, k-band, 24 ghz, sensor, distance, micro-movements
• LamaPLC: SGP Sensirion TVOC/VOC sensors with I <sup>2</sup> C communication	2026/04/15 19:41	sgp30, sgp40, sgp41, sensirion, gas-sensor, i <sup>2</sup> c, communication, sensor, arduino, code, eco <sub>2</sub> , voc, tvoc, indoor air quality, iaq, nox, hydrogen
• LamaPLC: SHT Sensirion Temperature/humidity sensor with I <sup>2</sup> C communication	2026/04/23 21:52	sht20, sht21, sht25, sht30, sht31, sht35, sht40, gy21, temperature, humidity, i <sup>2</sup> c, communication, sensor, arduino, code
• LamaPLC: Texas Instruments ADCs: Delta-sigma multi-channel Analog Converters with SPI communication	2026/04/23 21:52	ads111x, ads12xx, delta-sigma, converter, texas instruments, adc, spi, communication, sensor, arduino, code, ads1110, ads1112, ads1113, ads1114, ads1115, ads1118, ads1119, ads1220, ads1232, ads1234, ads1256, ads1261, ads1263, multi channel
• LamaPLC: TOFnnnC STMicroelectronics Time-of-Flight (ToF) sensors with I <sup>2</sup> C communication	2026/04/23 21:52	tof050c, vl6180, tof200c, vl5310x, tof400c, vl5311x, stmicroelectronics, time-of-flight, tof, i <sup>2</sup> c, communication, sensor, arduino, code
• LamaPLC: UICPAL Temp.humi.sensor	2023/06/25 00:43	simatic, s7, modbus, communication, temperature, humidity, sensor

- [LamaPLC: VL53Lnn STMicroelectronics time-of-flight \(ToF\) laser-ranging sensors with I<sup>2</sup>C communication](#) 2026/04/23 21:52 [vl53l0x, vl53l1x, vl53l0 1xv2, gy-530, time-of-flight, tof, laser-ranging, i2c, communication, sensor, arduino, code](#)
- [LamaPLC: VL6180X STMicroelectronics Time-of-Flight \(ToF\) sensor with I<sup>2</sup>C communication](#) 2026/04/23 21:52 [vl6180x, stmicroelectronics, time-of-flight, tof, i2c, communication, sensor, arduino, code](#)
- [LamaPLC: Waveshare TOF Laser Range Sensor with UART / I<sup>2</sup>C communication](#) 2026/04/23 21:52 [distance measurement, laser, range, sensor, tof, waveshare](#)
- [lamaPLC: YR-3180 - Weight sensor module with UART or Modbus communication](#) 2026/02/15 00:00 [communication, modbus, rtu, sensor, weight, yr-3180, hx710b, arduino, ttl, rs-485](#)
- [Magnetic angle sensors](#) 2026/03/05 21:19 [magnetic angle sensor, magnetic flux, sensor, spi, i2c, pwm, communication, modul, as5047p, as5600, mt6701, mt6816, mt6835, tle5012b, amr, gmr, tmr, anisotropic magnetoresistive](#)
- [NT18B07: 7 Kanal RS485 Temperatur Sensor with Modbus RTU](#) 2026/02/14 18:49 [nt18b07, sensor, modbus, rtu, rs-485, communication, platine](#)
- [PT100 / PT1000 sensors](#) 2026/04/23 21:52 [rtd, pt100, pt1000, sensor, temperature](#)
- [Radar Module RD-xx](#) 2026/04/23 21:52 [radar, s3km1110, fmcw, rd-03, k-band, 24 ghz, sensor, distance, micro-movements](#)

[magnetic angle sensor](#), [magnetic flux](#), [sensor](#), [SPI](#), [I2C](#), [PWM](#), [communication](#), [modul](#), [AS5047P](#), [AS5600](#), [MT6701](#), [MT6816](#), [MT6835](#), [TLE5012B](#), [AMR](#), [GMR](#), [TMR](#), [Anisotropic Magnetoresistive](#)

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