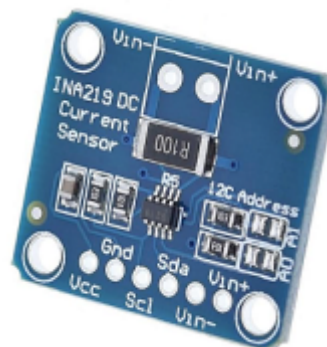


LamaPLC: CJMCU-219/INA-219 breakout board/IC with I²C communication

The **CJMCU-219** is a *breakout board* featuring the **INA219 IC**, a zero-drift, bidirectional current and power monitor with an **I²C** interface.



Core Technical Specifications

- **Voltage Measurement:** Can detect bus voltages from **0V to +26V DC**.
- **Current Range:** Measures **up to ±3.2A** bidirectionally using its built-in 0.1 ohm shunt resistor.
- **Supply Voltage:** Operates on **+3.0V to +5.5V**.
- **Precision:** Features a 12-bit ADC with a maximum error accuracy of 1% over -40°C to +85°C.
- **Interface:** Uses I²C communication (standard 100kHz or high-speed 400kHz/3.4MHz) with a default address of **0x40**.

Key Features

- **High-Side Sensing:** Unlike many sensors, it can measure current on the high side (between the power source and the load), thereby avoiding ground-reference issues.
- **Multi-Function Reporting:** It calculates and reports bus voltage, shunt voltage drop, current, and total power (W) directly.
- **Programmability:** Supports software-programmable calibration, filtering (averaging up to 128 samples), and conversion times.
- **Daisy-Chaining:** Supports up to 16 programmable I²C addresses, allowing multiple modules to run on the same bus.

Safety & Limitations

- **Voltage Limit:** The chip may be damaged if bus voltage exceeds its absolute hardware limit of 26V.
- **Inductive Loads:** Users should be cautious with large motors, as “flyback” voltage spikes can exceed the 26V threshold and destroy the sensor.

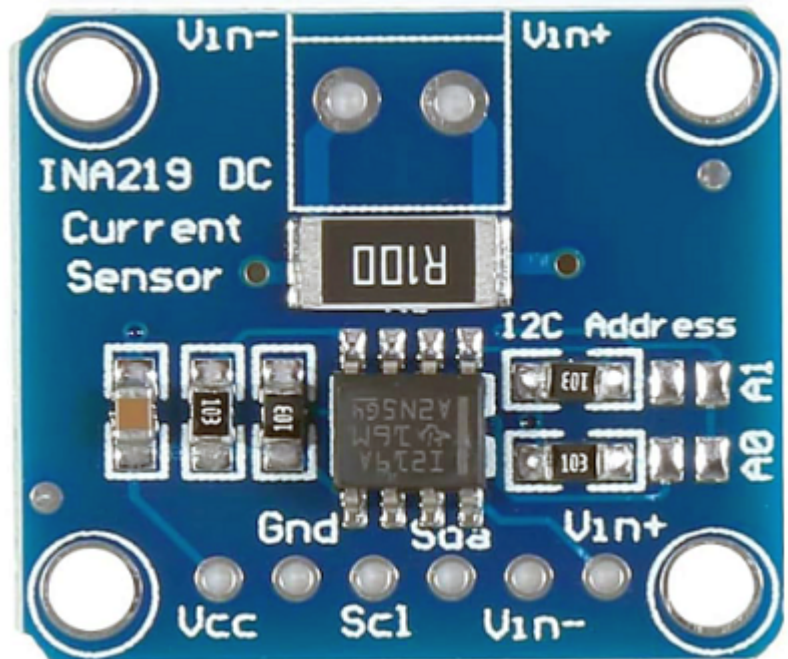


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CJMCU-219 Pinout

Logic and Power Pins



These pins connect to your microcontroller (e.g., Arduino or Raspberry Pi) to power the sensor and transmit data.

- **VCC:** Supply voltage for the module (**3.0V to 5.5V**).
- **GND:** Common ground for both power and logic.
- **SCL:** I²C serial clock line.
- **SDA:** I²C serial data line.

Measurement (Load) Pins

These pins are placed in series with the positive side (high-side) of the circuit you want to monitor.

- **Vin+:** Connect to the positive terminal of your power source (e.g., battery).
- **Vin-:** Connect to the positive terminal of your load (the device being powered).

I²C addressing Pins (A0 & A1)

Some versions of the CJMCU-219 include solder pads labeled **A0** and **A1**. By default, these are connected to GND, setting the I²C address to **0x40**.

Bridging these pads to VCC allows you to set the address to any of 16 values (**0x4F**), enabling multiple sensors on the same I²C bus.

Caution: The maximum bus voltage the Vin pins can safely handle is 26V DC.

Arduino wiring

- VCC → Arduino 5V (o 3.3V).
- GND → Arduino GND.

- SCL → Arduino SCL (A5 on Uno/Nano).
- SDA → Arduino SDA (A4 on Uno/Nano).
- Vin+ → Positive side of your power supply.
- Vin- → Positive side of your load (the device being powered).

Arduino code

To begin using the CJMCU-219 with Arduino, the easiest approach is to use the **Adafruit INA219** library.

This example code sets up the sensor and outputs voltage, current, and power readings to the Serial Monitor at **115200 baud**.

A simple example with the Adafruit_INA219 library involves initializing the sensor and repeatedly reading and displaying bus voltage, shunt voltage, load voltage, current, and power. The complete code is available in the provided source document.

```
#include <Wire.h>
#include <Adafruit_INA219.h>

Adafruit_INA219 ina219;

void setup(void) {
  Serial.begin(115200);
  while (!Serial) { delay(1); } // Wait for serial port to connect

  // Initialize the INA219 (default address 0x40)
  if (!ina219.begin()) {
    Serial.println("Failed to find INA219 chip");
    while (1) { delay(10); }
  }

  // Optional: Set calibration for higher precision
  // Default is 32V, 2A. Alternatives:
  // ina219.setCalibration_32V_1A();
  // ina219.setCalibration_16V_400mA();

  Serial.println("Measuring voltage and current with INA219...");
}

void loop(void) {
  float shuntvoltage = 0;
  float busvoltage = 0;
  float current_mA = 0;
  float loadvoltage = 0;
  float power_mW = 0;

  // Read data from sensor
  shuntvoltage = ina219.getShuntVoltage_mV();
  busvoltage = ina219.getBusVoltage_V();
```

```

current_mA = ina219.getCurrent_mA();
power_mW = ina219.getPower_mW();
loadvoltage = busvoltage + (shuntvoltage / 1000);

// Print results
Serial.print("Bus Voltage: "); Serial.print(busvoltage);
Serial.println(" V");
Serial.print("Shunt Voltage: "); Serial.print(shuntvoltage);
Serial.println(" mV");
Serial.print("Load Voltage: "); Serial.print(loadvoltage);
Serial.println(" V");
Serial.print("Current: "); Serial.print(current_mA);
Serial.println(" mA");
Serial.print("Power: "); Serial.print(power_mW); Serial.println("
mW");
Serial.println("");

delay(2000);
}

```

Key Functions Explained

- *begin()*: Starts I2C communication. It uses address 0x40 by default.
- *getBusVoltage_V()*: Returns the voltage between GND and the load (V-).
- *getShuntVoltage_mV()*: Returns the voltage drop across the 0.1 ohm resistor.
- *getCurrent_mA()*: Returns the current flowing through the sensor.
- *getPower_mW()*: Calculates power based on the current and bus voltage.

Calibration for Accuracy

The library includes built-in calibration modes to improve precision for specific ranges:

- **Default:** 32V, 2A (Used if no other function is called).
- **setCalibration_32V_1A():** Increases precision for current measurements up to 1A.
- **setCalibration_16V_400mA():** Highest precision for low-voltage, low-current projects.

I²C topics on lamaPLC

Page	Date	Tags
• lamaPLC Communication: 1-Wire	2026/04/23 21:51	1-wire , communication , bus , microlan , i2c , uart , usart , ds18b20
• lamaPLC Communication: I²C	2025/09/23 21:25	i2c , i c , smbus , philips , bus , communication , arduino
• LamaPLC: AHT10 Modul	2026/03/22 03:14	communication , i2c , temperature , humidity , sensor , aht , aht 10 , modul
• LamaPLC: AHT20 / BMP280 Modul	2026/04/23 21:52	bmp280 , aht20 , adafruit , temperature , humidity , pressure , sensor , arduino , code , i2c

- [LamaPLC: APDS - Avago ALS and proximity detection sensors with I²C communication](#) 2026/04/23 21:52

avago, apds-9900, apds-9930, apds-9960, als, proximity, detection, gesture recognition, gesture, i2c, communication, sensor, arduino, code
- [lamaPLC: AS5600 Magnetic Induction Angle Measurement Sensor Module](#) 2026/03/28 23:50

communication, i2c, as5600, as-5600, magnetic, induction, angle, sensor
- [lamaPLC: Bi-Directional Logic Level Converter 3.3V ↔ 5V](#) 2026/04/12 00:34

bi-directional, logic level converter, i2c, uart, spi
- [LamaPLC: BMP/BME Bosch Temperature/Humidity/Pressure sensors with I²C communication](#) 2026/04/23 21:52

bme280, bme680, bmp180, bmp280, hw-611, hw611, bosch, temperature, humidity, pressure, sensor, arduino, i2c, communication, cjmcu
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cjmcu-219, ina-219, ina219, breakout board, i2c, communication, sensor, voltage, current, arduino, code, cjmcu
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cjmcu-3216, cjmcu, ap-3216, ap3216, ambient light, proximity, sensor, arduino, code, i2c, communication
- [lamaPLC: CJMCU-811 CCS811 Gas Sensor \(VOCs TVOC CO2\)](#) 2026/03/22 00:08

cjmcu-811, ccs811, gas, sensor, vocs, tvoc, eco2, co2, arduino, air quality metal oxide, mox, i2c
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d6t, d6t-32l, d6t-44l, d6t-8l, d6t-1a, omron, non-contact, thermal, sensor, i2c, arduino, code
- [LamaPLC: DPS Infineon Temperature/Pressure sensors with I²C communication](#) 2026/04/23 21:52

dps310, infineon, temperature, pressure, sensor, arduino, i2c, communication, code
- [lamaPLC: Energy, power, current, and voltage](#) 2025/05/31 23:32

i2c, i c, communication, arduino, energy, power, current, sensor, ina226
- [LamaPLC: ENS ScioSense Multi-gas sensors with I²C communication](#) 2026/04/23 21:52

ens160, sciosense, gas-quality, i2c, communication, sensor, arduino, code, eco2, tvoc, aqi, indoor air quality, iaq, co2, voc
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esp8266, esp32, esp32-c2, esp32-c3, esp32-c5, esp32-c6, esp32-c61, esp32-h2, esp32-s2, esp32-s3, esp32-p4, espressif systems, communication, ethernet, ip, wi-fi, thread, zigbee, matter, homekit, bluetooth, mqtt, adc, spi, uart, i2c, i2s, rmt, pwm, usb, usb otg, twai
- [LamaPLC: Gas sensors](#) 2023/07/01 17:29

gas, sensor, i2c, onewire, communication, mq-3, mq-4, mq-5, mq-6, mq-7, mq-8, mq-9, mq-135, gm-102b, gm-302b, gm-502b, gm-702b, alcohol, ch4, natural gas, smoke, lng, co, co2, lpg, h2, iso-butane, nox, nh3, benzene, town gas, formaldehyde, propane, humidity, temperature, voc, grv gas sens v2

- [lamaPLC: GY-511 6DOF sensor module](#) 2026/03/22 01:44 [stmicroelectronics, lsm303dlhc, i2c, lsm303, sensor, gy-511, 6dof, pololu, module, arduino](#)
- [LamaPLC: GY-9250 MPU-9250/6500 9-axis Attitude Sensor Board](#) 2026/04/23 21:52 [ak8963, gy-9250, mpu-9250, 9-axis, motion detection, magnetometer, communication, i c, i2c, spi](#)
- [LamaPLC: HDC Texas Instruments Temperature/humidity sensors with I²C communication](#) 2026/04/23 21:52 [sht21, htu21, si7021, gy-21, gy-213v, hdc1080, gy-213v-hdc1080, cjmcu, cjmcu-1080, texas instruments, temperature, humidity, sensor, i2c, communication, arduino, code](#)
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- [LamaPLC: HTU TE Connectivity temperature/humidity sensors with I²C communication](#) 2026/04/23 21:52 [htu, htu31d, htu21d, htu20d, sht20, htu20, sht21, htu21, si7021, gy-21, gy-213v, hdc1080, si702, gy-20, sht31, htu31, si7031, gy-31, te connectivity, temperature, humidity, i2c, communication, sensor, arduino, code](#)
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- [LamaPLC: MAX30100/MAX30102 Heart Rate Click Sensor Module](#) 2026/04/23 21:52 [max30102, max30100, heart rate click, sensor, communication, i2c, arduino, code](#)
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- [LamaPLC: Pixart PAJ7620U2 Gesture recognition sensors/module with I²C communication](#) 2026/04/23 21:52 [paj7620u2, gy-paj7620, pixart, gesture recognition, i2c, communication, sensor, arduino, code](#)
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- [LamaPLC: SHT Sensirion Temperature/humidity sensor with I²C communication](#) 2026/04/23 21:52 [sht20, sht21, sht25, sht30, sht31, sht35, sht40, gy21, temperature, humidity, i2c, communication, sensor, arduino, code](#)
- [lamaPLC: Signal level converters](#) 2026/02/14 23:47 [pca9306, i2c, voltage, level, converter](#)

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 - [lamaPLC: TM1637 7-segment display](#)
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 - 2026/02/14
23:51
 - 2026/02/14
18:26
 - 2026/04/23
21:52
 - 2026/04/23
21:52
 - 2026/04/23
21:52

 - [tca9548a](#), [hw617](#), [i2c](#), [switch](#), [communication](#), [expansion board](#), [arduino](#)
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 - 2026/03/05
21:19

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 - 2026/02/14
18:27

 - [i2c](#), [oled](#), [display](#), [ssd1306](#), [sh1106](#), [ssh1106](#), [arduino](#), [cmos](#)

[CJMCU-219](#), [INA-219](#), [INA219](#), [breakout board](#), [i2c](#), [communication](#), [sensor](#), [voltage](#), [current](#), [arduino](#), [code](#), [CJMCU](#)

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